

TOEP: Threshold Oriented Energy Prediction Mechanism for MPI-OpenMP Hybrid Applications*

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Abstract—Evaluating the execution time and energy consumption of parallel programs is a primary research topic for many HPC environments. Whereas much work has been done to evaluate the non-functional behavior for single parallel programming models such as MPI or OpenMP, little work exists for hybrid programming models such as MPI/OpenMP. This paper proposes the Threshold Oriented Energy Prediction (TOEP) approach which uses the Random Forest Modeling (RFM) to train models for execution time and energy consumption of hybrid MPI/OpenMP programs. Training data (performance measurements) are reduced by ignoring code regions that have little impact on the overall energy consumption and runtime of a program and also based on the variable importance parameter of RFM. A selection parameter is introduced that selects a trade-off solution between the number of modeling points (measurement or training data) required and prediction accuracy. An exploratory study on the proposed prediction approach was employed for a few candidate hybrid applications namely HOMB, CoMD, and AMG2006-Laplace. The experimental results manifested the energy prediction accuracy of over 86.17% for large performance datasets of the candidate applications at a reduced computational effort of less than 17 seconds.

Index Terms—Energy Prediction, HPC, Hybrid, Scientific Applications

I. INTRODUCTION

The combined effort to control energy consumption without increasing execution times of parallel programs has become a major challenge for scientific applications on HPC systems [6]. Performance models are important to understand the non-functional behavior of parallel programs, to guide tools such as compilers and auto-tuners, to find good code transformation sequences, to understand work and data distribution strategies, to analyze performance sensitive SW and HW parameter values, and so forth. Much work has been conducted to examine the performance of single programming models including MPI and OpenMP. Hierarchical computer architecture organization is well suited for hybrid programming models such as MPI/OpenMP which is the focus of this paper. As multicore nodes with larger core counts and less memory per

node are becoming prevalent, it is anticipated [6] that hybrid programming models will be increasingly used. Whereas numerous works focused on performance and energy modeling for MPI and OpenMP as single programming models ([7], [15]), less work has been done to model both execution time and energy consumption of hybrid MPI / OpenMP programs.

This paper proposes a Threshold Oriented Energy Prediction mechanism for MPI-OpenMP Hybrid applications (TOEP). TOEP approach, in short, extracts the large performance data of applications; iteratively models and predicts the energy consumption of MPI-OpenMP hybrid applications starting from a few modeling points; applies a threshold oriented selection process which iteratively selects the best minimal modeling points while predicting the energy efficient problem sizes of MPI/OpenMP applications. The proposed approach could be applied in parallel compilers or autotuning tools. Iterations are carried out for the six pre-defined number of modeling points of Random Forest Modeling algorithm (discussed in Section III). The proposed approach was experimented for a few pilot MPI-OpenMP hybrid applications such as HOMB, CoMD, and AMG2006-Laplace on a four node computing cluster. The experimental results of TOEP approach have attained energy prediction accuracies of 83.3% to 99.01% and execution time prediction accuracies of up to 94%.

The rest of the paper is organized as follows: Section II presents the available energy prediction mechanisms for applications. Section III explains the TOEP approach for MPI/OpenMP applications. Section IV validates the proposed TOEP approach for the three candidate MPI/OpenMP applications namely HOMB, CoMD, and AMG2006-Laplace applications. And, finally, Section V presents a few conclusions.

II. RELATED WORK

Performance prediction of scientific applications is a complex problem as large number of variables is related both to the nature of the code (e.g. selective use of hardware features with impact on performance) and to the heterogeneous infrastructure. Researchers, in the past, had characterized and predicted the execution time of scientific applications. For instances, the authors of [19], [20] had mapped hardware profile details to

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applications; the authors of [11] had studied the application of historical data to predict the future executions; researchers of [3], [5], [12] had utilized statistical models while predicting execution time of applications; authors of [11], [18] had implemented data mining methods for the prediction problem of applications.

Analyzing performance concerns of applications is not considered to be the only target of modern HPC community. In recent years, therefore, several attempts have been carried out to reduce the energy consumption of scientific applications [1], [16], [17]. A few researchers have developed energy prediction and optimization approaches for HPC applications that are specific to MPI, OpenMP or CUDA applications. For instances, Bhavyasree et al [4] have proposed an energy optimization approach for MPI applications where Dynamic Voltage Frequency Scaling technique was applied on computing nodes; Shajulin et al [15] have implemented an energy prediction approach using RFM in compilers for OpenMP applications. These works were more specific to MPI or OpenMP applications. There exists a survey on energy modeling solutions for HPC applications by Brien et al (see [9]). In most of the existing modeling works, either the authors have dealt with single parallel programming models or have not considered the large performance datasets of emerging architectures. Our research work has deliberated over an energy prediction approach for MPI/OpenMP applications while observing the evolving large performance dataset from performance measurement tools.

III. TOEP – AN ENERGY PREDICTION APPROACH

The proposed TOEP approach aims at predicting the energy consumption and execution time of hybrid MPI/OpenMP applications. In TOEP, the energy / execution time predictions are carried out using RFM algorithm [10] consisting of the best possible minimal number of modeling points. The modeling points, specified in this paper, are the number of performance data utilized in the training dataset for RFM modeling. To select the best possible minimal number of modeling points in RFM, the modeling points of RFM are iteratively increased in TOEP based on the six pre-defined modeling methods; and, the corresponding best modeling method is chosen based on the threshold value obtained using the prediction accuracy of RFM and the effort (computation time) of TOEP.

A. TOEP Approach

Figure 1 illustrates the proposed TOEP approach with four phases as discussed below:

1) *Collection Phase*: At first, the performance dataset of a few selected code regions (for different problem sizes) are collected from the TAU based performance analysis mechanism which is utilized in this work (see sub section III-A5). In the case of MPI/OpenMP hybrid applications, the OpenMP parallel regions which follow MPI constructs are considered. Thus, the number of performance data that are available for energy modeling is substantially reduced. The performance measurement tool that we use for our work can produce 21

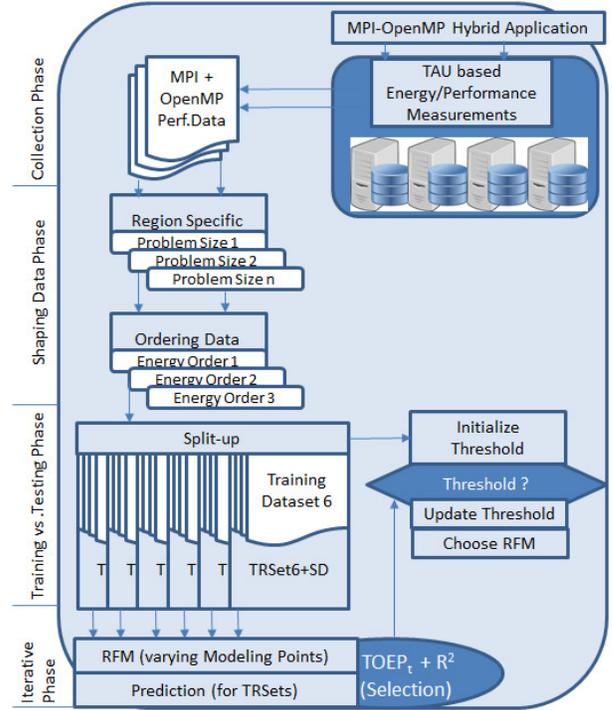


Fig. 1. Model Selection Mechanism of TOEP Approach

or even more different performance parameters based on the measurement requirements for applications.

2) *Shaping Data Phase*: Next, the energy consumption values from the reduced performance dataset are ordered in a decreasing order so that the energy modeling algorithms improve accuracy. The reason why such ordering improves accuracy of RFM is because the correlation between the independent variables and the dependent variables improves during the formation of random forest trees. In addition, the number of independent variables (i.e., the number of columns of the performance dataset) are reduced based on the variable importance parameter of RFM.

3) *Training vs. Testing Split-up Phase*: Here, the rows of these performance datasets are divided into training and testing datasets based on six pre-defined sampling methods adopted in this work. The sampling methods determine the number of modeling points of RFM. The training dataset is employed to create models and the testing dataset is utilized for predicting the energy/execution time of MPI/OpenMP applications based on the models created earlier. The six pre-defined sampling methods are named as TRSet1+SD, TRSet2+SD, TRSet3+SD, TRSet4+SD, TRSet5+SD, and TRSet6+SD (See Figure 1). In the sampling method TRSet1+SD, TRSet1 stands for a training set containing 1/2000 equi-distantly sampled rows of the whole performance dataset and SD stands for the dataset that has undergone the Shaping Data treatment mentioned in the previous phase; TRSet2+SD includes 1/1000 equi-distant sampling data; TRSet3+SD contains 1/100 data; TRSet4+SD includes 1/10 rows; TRSet5+SD contains 1/4 rows; and, TRSet6+SD contains 1/3 performance data.

4) *Iterative Phase*: In the iterative phase of TOEP, the following tasks are carried out for each of the six pre-defined sampling methods: a) *Threshold initiation*: At this stage, the threshold value T_i is initialized. Initially, it is set to zero. At the end of each iteration i , T_i is updated based on the *Selection* parameter as defined by Eq. (1). b) *Organizing Data*: Next, the training and testing datasets are stored in two different data frames. c) *RFM*: Later, RFM algorithm ([10]) is applied to the training dataset to create random forest trees which is a part of the learning process of the algorithm. In this work, the models are created for the energy consumption and execution time of the code regions of MPI-OpenMP hybrid applications. Afterwards, the created models are utilized to predict the energy consumption and execution times of MPI/OpenMP applications. The prediction accuracy of the RFM method when applied to each of the pre-defined sampling methods is calculated using R^2 . R^2 is the measure of goodness to the fitting model. d) *TOEP Computation time ($TOEP_t$)*: In addition to modeling and prediction steps, TOEP records the computation time (effort) for each iteration; In fact, $TOEP_t$ values are required to rank the pre-defined sampling methods. e) *Threshold based Selection*: For each iteration, the TOEP computation time ($TOEP_t$) and the prediction accuracy of each modeling methods (which were calculated using R^2) are evaluated through a *Selection* parameter as defined by Eq. (1). The *Selection* parameter is directly proportional to the prediction accuracy (R^2) and indirectly proportional to the computation time of TOEP ($TOEP_t$).

$$Selection = (R^2/TOEP_t) \quad (1)$$

Accordingly, the threshold value T_i is updated with newer values of the *Selection* parameter if the latest *Selection* parameter value is larger than T_i . By this, T_i will be revised with higher values for each iteration. In addition, at the end of this step, the corresponding best RFM modeling method (which relates to one of the six pre-defined sampling methods) will be elected for predicting the energy consumption and execution time of code regions of MPI/OpenMP applications based on the *Selection* parameter.

5) *Performance/Energy Measurements in TOEP*: Here, the OPARI2 [14] instrumentor of the TAU performance analysis framework is utilized for instrumenting OpenMP regions, whereas all MPI function calls are instrumented (i.e., adding additional functions to the programs in order to measure the performance values) by means of a wrapper library. The instrumented code regions of interest are compiled and input with possible problem sizes of hybrid applications. In order to control measurement overheads during program execution and ensure low measurement perturbation, a sophisticated *selective instrumentation* is tailored to each target application. By this, we restricted the instrumentation of applications to all MPI function calls and all OpenMP-annotated code regions of target applications. Then, the instrumented applications are executed on the target hardware platform with a given set of application-specific input problem sizes; the comprehensive performance data (regarding each region's execution time, energy consump-

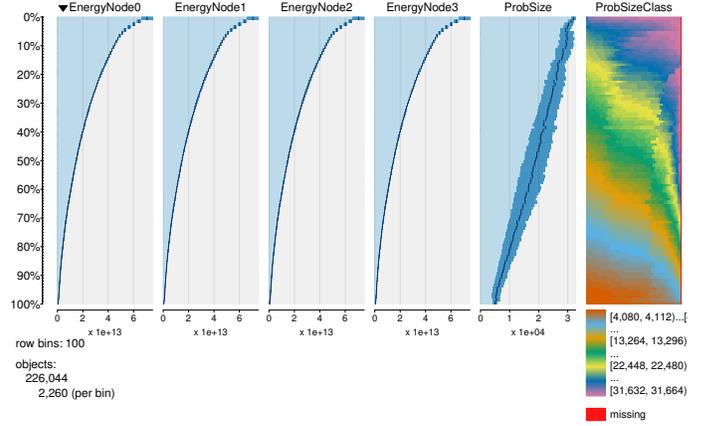


Fig. 2. Energy consumption values for different problem sizes of the HOMB application.

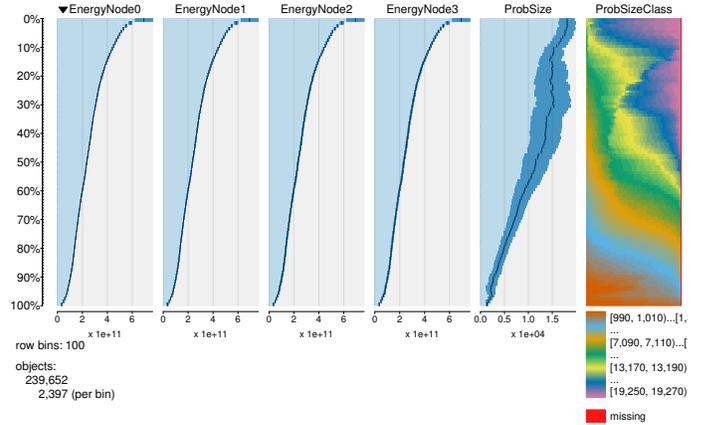


Fig. 3. Energy consumption values for different problem sizes of the COMD application.

tion, and hardware performance counter values) is collected. This data is then preprocessed and aggregated in order to be suitable for the subsequent prediction model training and validation (discussed in TOEP approach).

IV. EXPERIMENTAL RESULTS

This section explains the experimental setup; the energy consumption details of the pilot applications namely COMD [13], HOMB [8], and AMG2006-Laplace [2]; the energy modeling results of these applications; the impact of reducing the modeling points of RFM; and, the comparison of RFM based TOEP to the traditional Linear Regression Modeling (LRM) approach.

A. Experimental setup

In order to manifest the proposed TOEP approach, we have experimented three hybrid MPI-OpenMP applications: COMD, HOMB, and AMG2006-Laplace.

1) *Machines and Measurements*: The experimental target hardware platform consists of four nodes, each equipped with four Intel Xeon E5-4650 Sandy Bridge EP processors and 256 GB of main memory. HyperThreading is not in use for our

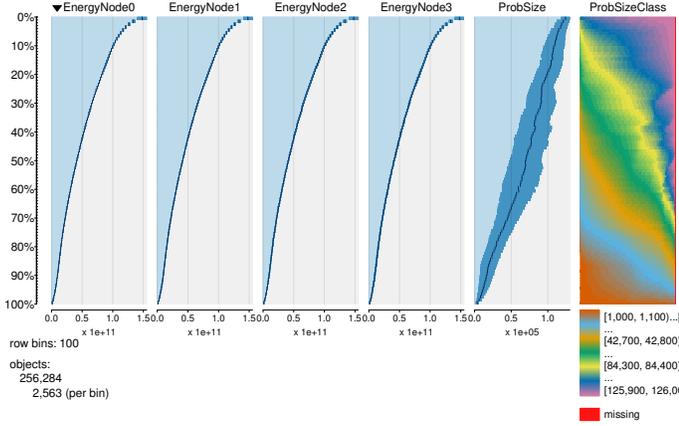


Fig. 4. Energy consumption values for different problem sizes of the AMG2006-Laplace application.

experiments (thus leading to a total of 32 hardware threads per node), and the clock rate is fixed to the highest nominal clock rate of 2.7 GHz (so that the energy measurements are valid). The nodes are connected via a dedicated Gigabit Ethernet network. The application binaries are compiled using gcc 6.3 with optimization level -O3. The nodes are clustered such that one MPI process is employed on each node with a varying number of OpenMP threads – 1, 2, 4, 8, 16, and 32 for our experiments. The process and thread combinations for the experiments are annotated as 4x1 (4 threads total), 4x2 (8 threads), 4x4 (16 threads), 4x8 (32 threads), 4x16 (64 threads), and 4x32 (128 threads). Thread binding is enforced in all experiments. During the experiments, the following hardware performance data were collected for each code region of applications: NumCalls, Inclusive_Time, Exclusive_Time, EnergyNodeN, PAPI_NATIVE_SIMD_FP_256, PAPI_NATIVE_LAST_LEVEL_CACHE_MISSES, PAPI_NATIVE_L1D:REPLACEMENT, PAPI_NATIVE_INSTRUCTION_RETIRED, PAPI_NATIVE_RESOURCE_STALLS:ANY.

Concisely, the performance dataset obtained for the experimental applications while considering different problem sizes reached hefty performance data sizes. For instances: the shaped performance data while considering only one OpenMP parallel region reached a performance data file size of 874.2 MB in HOMB application; similarly, CoMD had a file size of 3.2 GB; and AMG2006-Laplace had a file size of 1.9 GB.

B. Energy Consumption Values

Figures 2 to 4 illustrate the energy consumption value of applications available from the large performance dataset of applications, which consist of 226044 performance data entries (objects) for HOMB, 239652 objects for CoMD, and, 256284 data objects for AMG2006-Laplace applications. Each figure of Figures 2 to 4 consist of six columns. Column 1 to 4 reveal the increasing energy consumption values with respect to the problem sizes – in these columns, x-axis represent the energy consumption values in Joules and y-axis denote

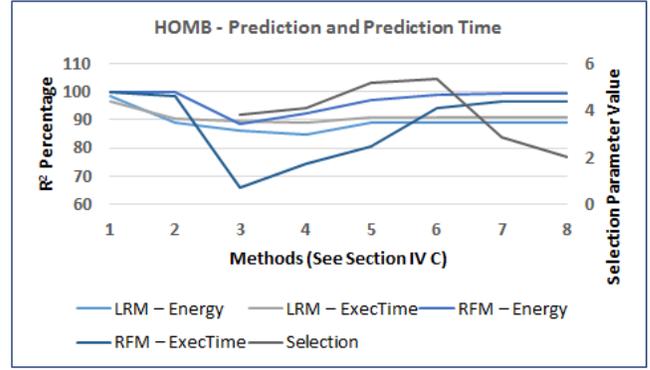


Fig. 5. Energy Prediction of HOMB using RFM and LRM

the performance dataset entries in percentage. For instance, in HOMB application, there were 226044 performance data objects. These data objects were binned into 100 equal bins (divisions) such that 2260 rows were plotted in the first bin. In addition, 100 percentage of x-axis in Figure 2 corresponds to the lowest problem size of HOMB (4096 in our case). Column 5 denotes the increasing problem size of applications, and Column 6 portrays the different classes of problem sizes of applications. The x-axis of column 5 of Figures 2 to 4 illustrate the problem size values of applications. The *Prob-SizeClass* column on the far right represent the grouping of the performance dataset in various classes based on the problem sizes of applications. Here, each class are represented with different color based on the increasing problem size.

C. TOEP Modeling Results

In TOEP, the performance data were utilized for modeling and predicting the energy consumption of different problem sizes of candidate hybrid applications.

1) *Modeling Datasets*: The number of problem sizes, the range of problem sizes, and the number of performance datasets available for modeling and predictions are listed in the Table I. It should be noticed that the performance dataset mentioned in Table I were filtered for the specific hybrid code regions of applications.

2) *Illustrations of Figures 5 to 7*:: Figures 5 to 7 explain the advantages of the proposed TOEP approach.

a) *Shaping Data and Variable Selection in TOEP*:: As discussed in Section III, TOEP shaped the raw performance dataset with more emphasis towards obtaining better prediction results for the energy consumption of hybrid code portion of applications (see the Shaping Data phase of Figure 1). To do so, it ordered the performance dataset in decreasing order before applying the RFM based energy modeling or prediction algorithms. In addition, as pointed out earlier, the measurement system produced over 21 performance variables which implicitly create heavy modeling time for applications. To avoid this hefty TOEP computation time (the effort), TOEP restricted the number of variables utilized for the modeling or predictions. The number of independent variables utilized for the modeling mechanisms of TOEP was

TABLE I
DETAILS OF PERFORMANCE DATASETS AND THE PROBLEM SIZE OF APPLICATIONS USED FOR OUR MODELING

Applications	No. of Problem Size	Problem Size	Number of Lines in Performance Dataset						
			All	4x32	4x16	4x8	4x4	4x2	4x1
HOMB	897	4096 to 32768	226044	113022	56511	28255	14127	7063	3531
CoMD	951	1000 to 20000	239652	119826	59913	29956	14978	7489	3744
AMG2006 Laplace	1017	1024 to 131072	256284	130176	65088	32544	16272	8136	4068

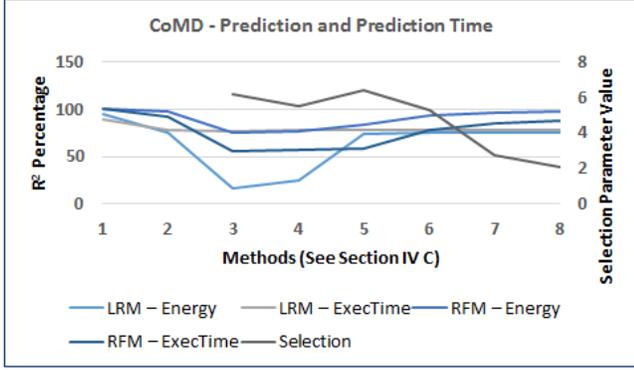


Fig. 6. Energy Prediction of CoMD using RFM and LRM

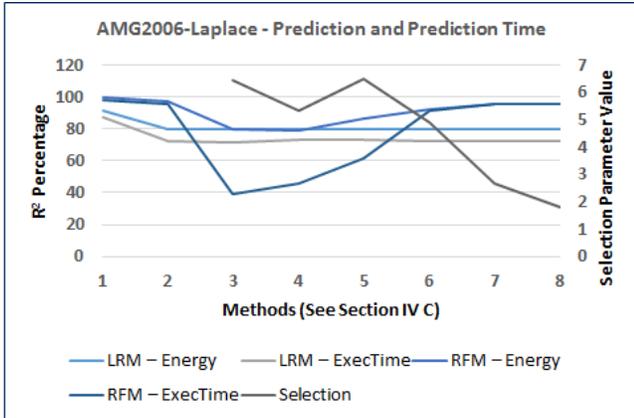


Fig. 7. Energy Prediction of AMG2006-Laplace using RFM and LRM

reduced to three variables based on expert experiences: i) PAPI_NATIVE_LAST_LEVEL_CACHE_MISSES, ii) Prob-Size, and iii) Inclusive ExecutionTime/EnergyNodeN.

b) *Modeling Methods – the utility of modeling points in RFM*:: Method 1, represented in the x-axis of the Figures 5 to 7, reveals the R^2 values of applications while ordering the energy consumption value of datasets. The y-axis of Figures 5 to 7 represents R^2 values in percentage. However, Method 1 has included all performance variables during the modeling and prediction process of RFM. Method 2, represented in the x-axis of the Figures 5 to 7, shows the R^2 values of applications combining Method 1 and reducing the number of independent variables of the models. Methods 3 to 8, represented in the x-axis of the Figures 5 to 7, illustrate the application of TOEP approach while implementing different pre-defined modeling points of RFM. Methods 3 to 8 included

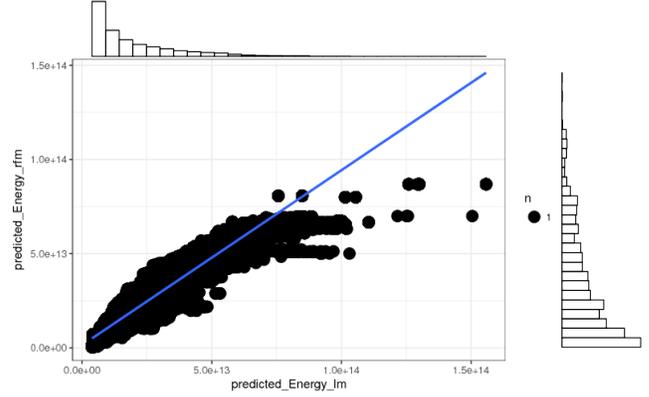


Fig. 8. RFM vs. LRM Marginal Histogram Plot for HOMB Application

Method 1 and Method 2 (i.e., the performance data were shaped and reduced to a minimal set of independent variables). It could be observed that the *Selection* parameter value is, thus, not included for the Methods 1 and 2. But, it is calculated from Methods 3 to 8, which reflect the TOEP approach.

c) *RFM Modeling in TOEP*:: RFM based predictions are implemented in TOEP approach for all associated methods: Methods 3 to 8 of Figures 5 to 7. As seen, the prediction results for the selective hybrid code portions of the candidate applications are depicted in the Figures in terms of R^2 . It could be observed that the R^2 values were higher for RFM when compared to LRM. In addition, the *Selection* parameter value is calculated and plotted on Figures 5 to 7 based on the TOEP computation time and the energy prediction accuracy (R^2) of RFM (see Equation 1). The secondary y-axis of Figures 5 to 7 explains the *Selection* parameter value of applications. As seen in Figures, TRSet4+SD modeling option was selected for HOMB application, TRSet3+SD was selected for CoMD and AMG2006-Laplace applications in TOEP approach.

D. Validation of TOEP Approach

Fixing the identified modeling options for each application, the energy consumption values of problem sizes of MPI/OpenMP applications were predicted in TOEP. The energy prediction values due to RFM based modeling in TOEP for candidate applications namely HOMB, CoMD, and AMG2006-Laplace reached the R^2 values of 99.01, 83.3, and 86.17. In contrary, LRM approach achieved only 88.88, 73.34, and 79.66. In addition, the TOEP computation time $TOEP_t$ for the applications were 17.56, 13.06, and 13.31 seconds for the candidate hybrid applications. Accordingly, the *Selection*

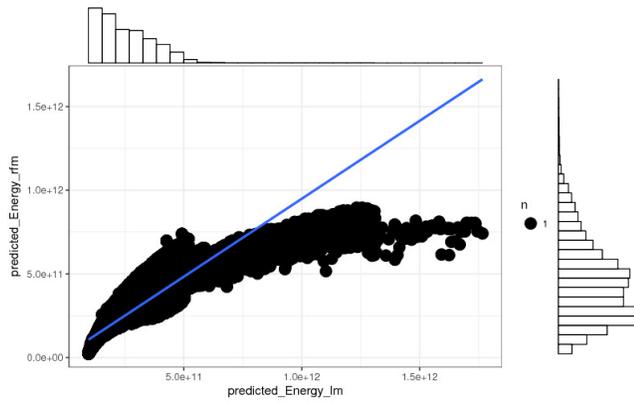


Fig. 9. RFM vs. LRM Marginal Histogram Plot for CoMD Application

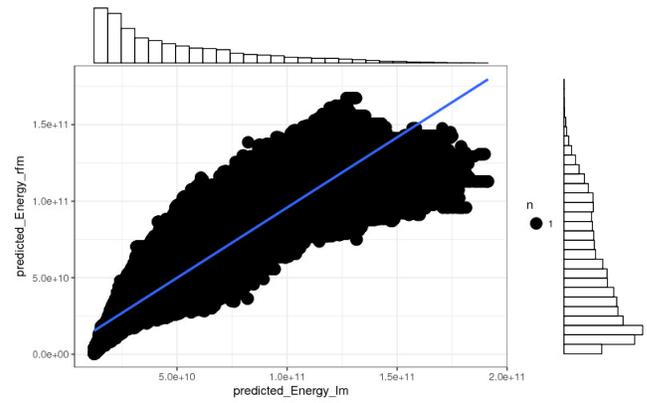


Fig. 10. RFM vs. LRM Marginal Histogram Plot for AMG2006-Laplace

parameter value revealed the following highest points: i) 5.35 points at TRSet4+SD option for HOMB application, ii) 6.37 points at TRSet3+SD for CoMD application, and iii) 6.47 points at TRSet3+SD for AMG2006-Laplace application. In Figures 8 to 10, we could observe the energy prediction values that were deviated from TOEP approach and LRM approach. Clearly, the proposed TOEP approach manifested better than LRM for the experimented MPI/OpenMP hybrid applications.

V. CONCLUSION

In this paper, we introduced the Threshold Oriented Energy Prediction (TOEP) approach using the Random Forest algorithm for predicting the energy consumption and execution time of hybrid MPI/OpenMP applications. In contrast to many works that are specific to MPI or OpenMP, our approach is generic and able to deal with large performance datasets. As part of TOEP we defined an iterative threshold parameter which selects a tradeoff solution between the number of modeling points required and prediction accuracy. Experiments were conducted on a 4 node compute cluster for a few pilot MPI/OpenMP applications such as HOMB, CoMD, and AMG2006-Laplace. The experimental results have manifested the importance of TOEP approach by achieving an energy prediction accuracy (coefficient of determination – R^2) of 83.3 to 99.01 % when compared to the traditional linear regression models of 73.34 to 88.88 %; similarly, an execution time prediction accuracy of up to 94.11 % (up to 90.96 % for LRM). In addition, the TOEP approach reduced the computational effort for prediction when compared to LRM. For our test applications, the computational effort for predictions with TOEP were about 13 to 17 seconds; whereas with LRM, the computational effort reached over 241.8 seconds.

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